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Amendments to the Claims

- 1. (Original) A method of determining a centroid of a target set in a wafer, said method comprising the steps of:
- a) receiving said wafer, said wafer having said target set formed therein, said target set including a plurality of target shapes separated by a material;
- b) passing a signal over said plurality of target shapes and over said material of said target set;
- c) receiving a return signal that is reflected from said plurality of target shapes
 and from said material separating said plurality of target shapes within said target set;
- d) identifying a location of each of at least one extrema of said return signal reflected from said material separating said plurality of target shapes within said target set; and
- e) determining said centroid of said target set from said at least one extrema of said return signal.
- 2. (Original) The method recited in Claim 1 wherein said extrema is a maxima point.
- 3. (Original) The method recited in Claim 1 wherein said signal is a laser signal.
- 4. (Original) The method recited in Claim 2 wherein said maxima point is determined from a slope of an intensity of said return signal, said slope existing on either side of said maxima point.
- 5. (Original) The method recited in Claim 1 wherein said plurality of target shapes includes two rectangular target shapes.

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- 6. (Original) The method recited in Claim 5 wherein only one maxima point is generated.
- 7. (Original) The method recited in Claim 6 wherein said centroid is located at said one maxima point.
- 8. (Original) The method recited in Claim 1 wherein said plurality of target shapes includes four rectangular target shapes.
- 9. (Original) The method recited in Claim 8 wherein said extrema of said step d) are comprised of three maxima points, said three maxima points including two outer maxima points and a center maxima point.
- 10. (Original) The method recited in Claim 9 wherein a location of said centroid is based on a median location between said two outer maxima points, averaged with a location of said center maxima point.
- 11. (Original) The method recited in Claim 9 wherein a location of said centroid is based on a centroid calculation using a location of all three maxima points.
- (Currently Amended) A stepper for aligning a wafer, said stepper comprising:
 a processor; and
- a computer readable memory, said computer readable memory coupled to said processor, said computer readable memory containing program instructions stored therein

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that when executed over said by said processor implement a method for determining a centroid of a target set in said wafer, said method comprising the steps of:

- a) receiving said wafer, said wafer having said target set formed therein, said target set including a plurality of target shapes separated by a material;
- b) passing a signal over said plurality of target shapes and over said material of said target set;
- c) receiving a return signal that is reflected from said plurality of target shapes and from said material separating said plurality of target shapes within said target set;
- d) identifying a location of each of at least one extrema of said return signal from said material separating said plurality of target shapes within said target set; and
- e) determining said centroid of said target set from said at least one extrema of said return signal.
- 13. (Currently Amended) The method recited in Claim 12 The stepper as recited in claim 12, wherein said signal is a laser light signal.
- 14. (Curently Amended) The method recited in Claim 12 The stepper as recited in claim 12, wherein said extrema is a maxima point determined from a slope of said intensity an intensity of said return signal, said slope existing on either side of said maxima point.

Claims 15-22 (Cancelled)